

**SOME CHARACTERIZATIONS OF THREE-DIMENSIONAL
TRANS-SASAKIAN MANIFOLDS ADMITTING η -RICCI SOLITONS
AND TRANS-SASAKIAN MANIFOLDS AS KAGAN SUBPROJECTIVE SPACES**

**ДЕЯКІ ХАРАКТЕРИСТИКИ ТРИВИМІРНИХ ТРАНС-МНОГОВИДІВ
САСАКЯНА, ЩО ДОПУСКАЮТЬ η -СОЛІТОНІ РІЧЧІ,
ТА ТРАНС-МНОГОВИДИ САСАКЯНА ЯК СУБПРОЕКТИВНІ
ПРОСТОРИ КАГАНА**

The object of the present paper is to study three-dimensional trans-Sasakian manifolds admitting η -Ricci soliton. Actually, we study such manifolds whose Ricci tensor satisfy some special conditions like cyclic parallelity, Ricci semisymmetry, ϕ -Ricci semisymmetry, after reviewing the properties of second order parallel tensors on such manifolds. We determine the form of Riemann curvature tensor of trans-Sasakian manifolds of dimension greater than three as Kagan subprojective spaces. We also give some classification results of trans-Sasakian manifolds of dimension greater than three as Kagan subprojective spaces.

Вивчаються тривимірні транс-многовиди Сасакаяна, які допускають η -солітони Річчі. Власне, після огляду властивостей паралельних тензорів другого порядку на таких многовидах ми вивчасмо многовиди, тензор Річчі яких задовольняє деякі спеціальні умови, такі як циклічна паралельність, напівсиметрія Річчі, ϕ -напівсиметрія Річчі. Визначено форму тензора кривини Рімана для транс-многовидів Сасакаяна, розмірність яких більша ніж 3, як субпроективних просторів Кагана. Також наведено деякі класифікаційні результати для транс-многовидів Сасакаяна, розмірність яких більша ніж 3, як субпроективних просторів Кагана.

1. Introduction. In [18], R. S. Hamilton introduced the revolutionary concept of Ricci flow on surfaces. The concepts of Ricci flow in physics was introduced by Friedan [14] almost around in the same time but with different motivations. Now a days such geometric flows have become popular, largely, because of Perelman's [22] work which lead to the proof of well known Poincaré conjecture. A Ricci soliton is a special solution of Ricci flow. This is considered as a natural generalization of Einstein metric and is defined on a Riemannian manifold (M, g) by

$$(\mathcal{L}_V g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) = 0, \quad (1.1)$$

where \mathcal{L}_V denotes the Lie derivative operator along a complete vector field V . V is known as potential vector field. λ is a constant, called soliton constant. S is the Ricci tensor and g is the metric. X, Y are the arbitrary vector fields on M . The Ricci soliton is said to be shrinking, steady or expanding as λ is negative, zero or positive, respectively [7]. The study of Ricci solitons on contact manifolds was initiated by R. Sharma [24]. Later several authors have studied Ricci soliton on almost contact manifolds. For example, we may refer the papers [12, 15, 16, 27]. In [5], it has been proved that a real hypersurface in a non-flat complex space form does not admit a Ricci soliton with ξ as soliton vector field and then the author adopted the notion of η -Ricci soliton. The η -Ricci soliton (g, ξ, λ, μ) on a Riemannian manifold is defined by

$$\mathcal{L}_\xi g + 2S + 2\lambda - 2\mu n \otimes n = 0,$$

where ξ is the Reeb vector field, μ is a constant and the other objects are as described in equation (1.1). For details see also [2, 6, 8, 23]. Since 1923 [13], second order parallel tensors are studied

by several authors [20]. Second order parallel tensors were studied in the frame work of contact manifolds by R. Sharma [25].

If geodesics are represented by $n - 2$ homogeneous linear equations for a suitable coordinate system in an affine space A_n , then A_n is called a subprojective space by B. Kagan [19]. T. Adati [1] have studied such spaces intensively and proved that Kagan subprojective spaces are conformally flat [1, p. 160]. In this paper, we would like to find form of Riemann curvature tensors of trans-Sasakian manifolds of dimension greater than three as Kagan subprojective spaces. We give some classification results of such spaces.

2. Preliminaries. Let M be a differentiable manifold of dimension $2n + 1$. M is said to have almost contact structure [3] if there is a (1,1) tensor field ϕ , a vector field ξ and a 1-form η on M such that

$$\phi^2 X = -X + \eta(X)\xi, \quad \eta(\xi) = 1,$$

where $X \in \chi(M)$, the set of all differentiable vector fields on M . On such manifolds it can be also proved that

$$\phi\xi = 0, \quad \eta(\phi X) = 0, \quad g(X, \phi Y) = -g(\phi X, Y), \quad g(X, \xi) = \eta(X)$$

for $X, Y \in \chi(M)$. An almost contact structure is called almost contact metric structure if there exists a Riemannian metric g on M satisfying

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y).$$

The (0,2) tensor field Φ defined by $\Phi(X, Y) = g(X, \phi Y)$ is known as fundamental 2-form of the manifold. If Φ is closed, an almost contact metric structure reduces to contact metric structure [3]. An almost contact metric structure (ϕ, ξ, η, g) on a differentiable manifold M is called a trans-Sasakian structure [21] if $(M \times R, J, G)$ belongs to the class W_4 in the Gray–Hervella classification [17]. Here J is the almost complex structure on $M \times R$ defined by $J\left(X, f\frac{d}{dt}\right) = \left(\phi X - f\xi, \eta(X)\frac{d}{dt}\right)$, for all vector fields X on M and smooth functions f on $M \times R$ and G is the product metric on $M \times R$. This fact may be formulated by the following equation [4]:

$$(\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\phi X, Y)\xi - \eta(Y)\phi X),$$

where α and β are smooth functions on M . The above formula implies

$$\nabla_X \xi = \beta(X - \eta(X)\xi) - \alpha\phi X, \tag{2.1}$$

$$(\nabla_X \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y). \tag{2.2}$$

The Ricci tensor [11] of a three-dimensional trans-Sasakian manifold is given by

$$\begin{aligned} S(X, Y) = & \left(\frac{r}{2} + \xi\beta - (\alpha^2 - \beta^2)\right)g(X, Y) - \left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(X)\eta(Y) - \\ & -(Y\beta + (\phi Y)\alpha)\eta(X) - (X\beta + (\phi X)\alpha)\eta(Y), \end{aligned} \tag{2.3}$$

where r is the scalar curvature of the manifold. Again from [9], we known that the Riemann curvature of a three-dimensional trans-Sasakian manifold is given by

$$\begin{aligned}
R(X, Y)Z &= \left(\frac{r}{2} + 2\xi\beta - 2(\alpha^2 - \beta^2)\right) (g(Y, Z)X - g(X, Z)Y) - \\
&-g(Y, Z) \left[\left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right) \eta(X)\xi - \eta(X)(\phi\text{grad } \alpha - \text{grad } \beta) + \right. \\
&+ (X\beta + (\phi X)\alpha)\xi] + g(X, Z) \left[\left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right) \eta(Y)\xi - \eta(Y)(\phi\text{grad } \alpha - \text{grad } \beta) + \right. \\
&+ (Y\beta + (\phi Y)\alpha)\xi] - \left[(Z\beta + (\phi Z)\alpha)\eta(Y) + (Y\beta + (\phi Y)\alpha)\eta(Z) + \right. \\
&+ \left. \left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right) \eta(Y)\eta(Z) \right] X + \left[(Z\beta + (\phi Z)\alpha)\eta(X) + \right. \\
&+ \left. (X\beta + (\phi X)\alpha)\eta(Z) + \left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right) \eta(X)\eta(Z) \right] Y. \tag{2.4}
\end{aligned}$$

Again

$$2\alpha\beta + \xi\alpha = 0.$$

3. Existence criteria of η -Ricci soliton on three-dimensional trans-Sasakian manifolds.

Theorem 3.1. *A three-dimensional trans-Sasakian manifold with constant ξ -sectional curvature admits η -Ricci soliton if and only if $\mathcal{L}_\xi g + 2S + 2\mu n \otimes n$ is parallel.*

Theorem 3.2. *A three-dimensional proper trans-Sasakian manifold with cyclic parallel Ricci tensor does not admit η -Ricci soliton. It reduces to Einstein manifold.*

Proof. Let $(M, g, \xi, \lambda, \mu)$ be a three-dimensional trans-Sasakian η -Ricci soliton. Then we have

$$(\mathcal{L}_\xi g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta(X)\eta(Y) = 0.$$

Expressing the Lie derivative in terms of covariant derivative and using (2.1), we obtain

$$S(X, Y) = -\frac{2\lambda + \beta}{2}g(X, Y) + \frac{2\mu - \beta}{2}\eta(X)\eta(Y). \tag{3.1}$$

In [12], it was proved that if T is a symmetric parallel tensor on a trans-Sasakian manifold of dimension three with non-zero ξ -sectional curvature, then

$$T(X, Y) = T(\xi, \xi)g(X, Y).$$

We see that $(\mathcal{L}_\xi g)(X, Y) + 2S(X, Y) + 2\mu\eta(X)\eta(Y)$ is a symmetric $(0, 2)$ tensor. Hence, by using its property, we obtain Theorem 3.1. Consider the manifold has cyclic parallel Ricci tensor [9]. By virtue of (3.1) and (2.3), after simplification we have $S = -\frac{2(\lambda + \beta)}{2}g$.

Theorem 3.2 is proved.

4. Ricci semisymmetric three-dimensional trans-Sasakian manifold admitting η -Ricci soliton.

Theorem 4.1. *If a three-dimensional trans-Sasakian manifold of type (α, β) , where $\alpha \neq \pm\beta$ and $\beta = \text{constant}$, admitting η -Ricci soliton is Ricci semisymmetric, then $\mu = \frac{\beta}{2}$.*

Corollary 4.1. *A Ricci semisymmetric three-dimensional α -Sasakian manifold does not admit proper η -Ricci soliton.*

Proof. It is well known that a Riemannian manifold is called Ricci semisymmetric if

$$(R(X, Y)S)(U, V) = 0.$$

The above condition implies

$$S(R(X, Y)U, V) + S(U, R(X, Y)V) = 0.$$

Putting $Y = V = \xi$, we have

$$S(R(X, \xi)U, \xi) + S(U, R(X, \xi)\xi) = 0.$$

Using (2.4) in the above equation, after straight forward computation we have $\mu = \frac{\beta}{2}$, provided $\alpha \neq \pm\beta$. So, we have Theorem 4.1 for α -Sasakian case $\alpha = \text{constant}$ and $\beta = 0$. Thus we have Corollary 4.1.

5. ϕ -Ricci symmetric three-dimensional trans-Sasakian manifold admitting η -Ricci soliton.

The notion of ϕ -Ricci symmetry was given by the first author in [10]. An almost contact manifold is called ϕ -Ricci symmetric if the Ricci operator Q satisfies

$$\phi^2(\nabla_W Q)X = 0.$$

The manifold is called locally ϕ -Ricci symmetric if X and W are orthogonal to ξ .

Theorem 5.1. *A three-dimensional trans-Sasakian manifold admitting η -Ricci soliton is ϕ -Ricci symmetric if and only if $\mu = \frac{\beta}{2}$.*

Proof. By virtue of (3.1) we obtain

$$QX = -\frac{2\lambda + \beta}{2}X + \frac{2\mu - \beta}{2}\eta(X)\xi.$$

Hence,

$$\phi^2(\nabla_W Q)X = \alpha \left(\frac{\beta}{2} - \mu \right) \eta(X)\phi^2(\phi W) + \beta \left(\mu - \frac{\beta}{2} \right) \phi^2 W.$$

The above equation proves Theorem 5.1.

6. Form of Riemann curvature tensors of trans-Sasakian manifolds of dimension greater than three as Kagan subprojective spaces. Riemann curvature tensors for three-dimensional trans-Sasakian manifolds have been deduced in the paper [11]. In this section, we like to deduce the form of Riemann curvature tensors of trans-Sasakian manifolds of dimension greater than three as Kagan subprojective spaces [19].

Theorem 6.1. *The form of Riemann curvature tensor of a trans-Sasakian manifold of dimension greater than three as Kagan subprojective space is given by*

$$\begin{aligned} R(X, Y)Z = & \left(\frac{r}{2m(2m-1)} - \frac{2}{2m-1} \left(\frac{r}{2m}(\alpha^2 - \beta^2) \right) \right) (g(Y, Z)X - g(X, Z)Y) + \\ & + \frac{1}{2m-1} \left(\frac{r}{2m} + (2m+1)(\alpha^2 - \beta^2) \right) (\eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y). \end{aligned}$$

Theorem 6.2. *A trans-Sasakian manifold of dimension greater than three as Kagan subprojective space is Einstein manifold. Hence, it does not admit Ricci soliton and η -Ricci soliton.*

Proof. T. Adati [1] have proved that Kagan subprojective spaces are conformally flat. We know that the Weyl conformal curvature tensor C of a $(2m + 1)$ -dimensional ($m > 1$) manifold is given by

$$C(X, Y)Z = R(X, Y)Z - \frac{1}{2m - 1} [g(Y, Z)QX - g(X, Z)QY + S(Y, Z)X - S(X, Z)Y] + \frac{r}{2m(2m - 1)} [g(Y, Z)X - g(X, Z)Y],$$

where S is Ricci tensor and Q is Ricci operator. Since Kagan subprojective spaces are conformally flat, we get

$$R(X, Y)Z = \frac{1}{2m - 1} [g(Y, Z)QX - g(X, Z)QY + S(Y, Z)X - S(X, Z)Y] - \frac{r}{2m(2m - 1)} [g(Y, Z)X - g(X, Z)Y].$$

From the above equation, we find S and Q and obtain the results.

7. Some classification results of a trans-Sasakian manifold of dimension greater than three as Kagan subprojective space.

Definition 7.1. A Riemannian manifold is called locally ϕ -symmetric [26] if

$$\phi^2(\nabla_W R)(X, Y)Z = 0,$$

for X, Y, Z orthogonal to ξ .

Theorem 7.1. A trans-Sasakian manifold of dimension greater than three as Kagan subprojective space is locally ϕ -symmetric if and only if $\frac{dr}{2m} = 4(\alpha d\alpha - \beta d\beta)$.

Theorem 7.2. If the structure functions α and β of a trans-Sasakian manifold of dimension greater than three as Kagan subprojective space are same, then the manifold is locally ϕ -symmetric if and only if the scalar curvature of the manifold is constant.

Theorem 7.3. If the structure functions α and β of a trans-Sasakian manifold of dimension greater than three as Kagan subprojective space are constants, then the manifold is locally ϕ -symmetric.

Proof. By using Theorem 6.1, we get

$$\begin{aligned} & \phi^2(\nabla_W R)(X, Y)Z = \\ & = \left(\frac{dr}{2m(2m - 1)} - \frac{2}{2m - 1} \left(\frac{dr}{2m} + 2(\alpha d\alpha - \beta d\beta) \right) \right) (g(X, Z)Y - g(Y, Z)X), \end{aligned} \quad (7.1)$$

for X, Y, Z orthogonal to ξ . Let us consider the following cases:

Case 1. Consider α and β as arbitrary functions:

Subcase 1.1: Let $\alpha \neq \beta$. In that case we get Theorem 7.1 from (7.1).

Subcase 1.2: Let α and β are equal functions. In that case $\alpha d\alpha - \beta d\beta = 0$. So, we obtain Theorem 7.2 from (7.1).

Case 2. Let α and β are constants. In that case, deducing S from R , we have Theorem 7.3.

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