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The article is devoted to the study of one class of nonstationary random processes in the frame of the correlation theory. New model conceptions for infinitesimal correlation functions are found. Using such approach it is also possible to obtain canonical representations which are analogous to the spectral decomposition of a stationary random process and can be obtained using the theory of associated open systems.

Key words: *nonstationary random processes, nonselfadjoint operator, associated open system.*

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4.
                              $\varsigma(t)$ c

$$K(t,s) = M\varsigma(t)\overline{\varsigma(s)},$$

$$x_t \in M_\varsigma = \overline{V_k \varsigma(t_k)}$$

     :

$$\begin{cases} iA\dfrac{dx(t)}{dt} + x(t) = 0 \\ x|_{t=0} = x_0 \end{cases} \tag{1}$$

     , $K(t,s) = \langle x_t, x_s \rangle_{H_\varsigma}$.

                                        :

$$\begin{cases} iA\dfrac{dx}{dt} + x = \{u \\ v = u + \{^+ \dfrac{dx}{dt} \end{cases} \tag{2}$$

$$\dfrac{A - A^*}{i} = \{\{^+, \ \{^+ = J\{^*, \ J \ - \qquad , \ . \ . \qquad A \in X ,$$

$X = (A, H, \{, E, J) -$.

     (2) $\dfrac{d}{dt}\|x\|_H^2 = [v,v]_E - [u,u]_E$.

              .

          (1) T_t $x_t = T_t \varsigma_0$.

     , T_t :

$$\begin{cases} iA\dfrac{dT_t}{dt} + T_t = 0 \\ T_t|_{t=1} = I \end{cases} \tag{3}$$

$$Z_t = -\frac{1}{2fi}\oint_X e^{it}\left(\}A-I\right)^{-1}Ad\} ,$$

$\left(\}A-I\right)^{-1}A$ – . :

$$\frac{dZ_t}{dt} = -\frac{i}{2fi}\oint_X e^{it}\left(\}A-I\right)^{-1}d\} \qquad (4)$$

(4) iA , : $iA\dfrac{dZ_t}{dt} = -\dfrac{-1}{2fi}\oint_X e^{it}\left(\}A-I\right)^{-1}Ad\}$, . .

$iA\dfrac{dZ_t}{dt} = -Z_t$. , $iA\dfrac{dZ_t}{dt}+Z_t = 0$, Z_t T_t

.

A – , Z_0 :

$$Z_0 = -\frac{1}{2fi}\oint_X\left(\}A-I\right)^{-1}Ad\} = -\frac{1}{2fi}\oint_X\frac{\left(I-\dfrac{A^{-1}}{\}}\right)^{-1}}{\}}d\} .$$

$$|\}| \geq \max\left(\|A\|,\|A^{-1}\|\right), \qquad \left(I-\frac{A^{-1}}{\}}\right)^{-1} = I+\frac{A^{-1}}{\}}+\frac{A^{-2}}{\}^2}+..., $$

$$\left\|\frac{A^{-1}}{\}}\right\| = \frac{1}{|\}|}\|A^{-1}\| < 1 .$$

$$Z_0 = -\frac{1}{2fi}\oint_X\frac{d\}}{\}}I+... = I .$$

, Z_t (3) ,

, $Z_t = T_t$.

$W(t,s) = \langle 2\operatorname{Im}Ax_t, x_t\rangle_H$ [5].

1.

:

$$\frac{\partial^2 W(t,s)}{\partial t\partial s} = \left(\frac{\partial}{\partial t}+\frac{\partial}{\partial s}\right)K(t,s).$$

.   (2)   :

$$\left\langle iA\frac{dx_t}{dt},\frac{dx_s}{ds}\right\rangle_H+\left\langle \frac{dx_t}{dt},iA\frac{dx_s}{ds}\right\rangle_H=-\left\langle x_t,\frac{dx_s}{ds}\right\rangle_H-\left\langle \frac{dx_t}{dt},x_s\right\rangle_H;$$

$$\left\langle iA\frac{dx_t}{dt},\frac{dx_s}{ds}\right\rangle_H+\left\langle -iA^*\frac{dx_t}{dt},\frac{dx_s}{ds}\right\rangle_H=-\left\langle x_t,\frac{dx_s}{ds}\right\rangle_H-\left\langle \frac{dx_t}{dt},x_s\right\rangle_H;$$

$$-\left\langle 2\operatorname{Im}A\frac{dx_t}{dt},\frac{dx_s}{ds}\right\rangle_H=-\left(\frac{\partial}{\partial t}+\frac{\partial}{\partial s}\right)K(t,s);$$

$$-\frac{\partial^2}{\partial t\partial s}\langle 2\operatorname{Im}Ax_t,x_s\rangle_H=-\left(\frac{\partial}{\partial t}+\frac{\partial}{\partial s}\right)K(t,s);$$

$$-\left(\frac{\partial}{\partial t}+\frac{\partial}{\partial s}\right)K(t,s)=\frac{\partial^2}{\partial t\partial s}\langle 2\operatorname{Im}Ax_t,x_s\rangle_H=\frac{\partial^2}{\partial t\partial s}W(t,s)\qquad(5)$$

$$\frac{\partial^2}{\partial t\partial s}W(t,s)=-V(t,s).$$

(5)   , $A=A^*$, $2\operatorname{Im}A=0$ $\left(\dfrac{\partial}{\partial t}+\dfrac{\partial}{\partial s}\right)K(t,s)=0$.

, $K=K(t-s)$.

,   ,   (1),

.

2. $\dim\overline{2\operatorname{Im}AH}=r<\infty$,

$$\left(\frac{\partial}{\partial t}+\frac{\partial}{\partial s}\right)K(t,s)=\sum_{r,s=1}^{r}\mathcal{E}_r(t)I_{rs}\overline{\mathcal{E}_s(s)},$$

$$\mathcal{E}_r(t)=\left\langle \frac{dx_t}{dt},g_r\right\rangle_H=\frac{d}{dt}\langle x_t,g_r\rangle_H=\frac{d}{dt}\langle T_tx_0,g_r\rangle_H=\frac{d}{dt}\langle x_0,T_t^*g_r\rangle_H.$$

:

$$\left\langle 2\operatorname{Im}A\frac{dx_t}{dt},\frac{dx_s}{ds}\right\rangle_H=\frac{\partial^2}{\partial t\partial s}\langle 2\operatorname{Im}Ax_t,x_s\rangle_H=\frac{\partial^2}{\partial t\partial s}\sum_{r,s=1}^{r}\{_r(t)I_{rs}\overline{\{_s(s)},$$

$$:\ 2\operatorname{Im}A=\sum_{r,s=1}^{r}\langle\cdot,g_r\rangle I_{rs}\overline{g_s}\ ,\ g_r\ -$$

A, $\{_r(t)=\langle x_t,g_r\rangle_H$ [5].

$$, \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial s}\right) K(t,s) = -V(t,s).$$

$$K(t,s) = \begin{cases} K(t-s,0) + \int\limits_0^{-s} V(t+\ddagger, s+\ddagger)d\ddagger, \ t \geq s \\ K(0,s-t) + \int\limits_0^{-t} V(t+\ddagger, s+\ddagger)d\ddagger, \ s \geq t \end{cases} \tag{6}$$

. , $\text{Œ}_{\mathsf{r}}(t) = \left\langle \dfrac{dx}{dt}, g_{\mathsf{r}} \right\rangle_H$

.

A – $\{\}_k\}$ (. .

$$\}_k = \mathsf{r}_k - i\frac{\mathsf{s}_k^2}{2}, \ \mathsf{s}_k \neq 0, \qquad \sum_{k=1}^{\infty} \mathsf{s}_k^2 < \infty)$$

$$K = \left(A, l_2, g = \begin{pmatrix} \mathsf{s}_1 \\ \mathsf{s}_2 \\ \vdots \end{pmatrix}, \left(I_{\mathsf{rs}}\right) = -1 \right), \ \dim \overline{2\,\text{Im}\,AH} = 1. \qquad \text{Œ}(t).$$

$$\text{Œ}(t) = \frac{d}{dt}\left\langle T_t x_0, g \right\rangle_{l_2} = \frac{d}{dt}\left\langle x_0, T_t^* g \right\rangle_{l_2}, \ \overline{\left(T_t^* g\right)}_k = \Lambda_k(t).$$

$$\text{Œ}(t) = \sum_{k=1}^{\infty} x_0(k)\Lambda_k'(t),$$

$$\Lambda_k(t) = \left(T_t^* g\right)_k = \overline{-\frac{1}{2fi}\oint\limits_{\mathsf{x}} e^{-i\}t}\left(\left(A^*\} - I\right)^{-1} A^* g\right)_k d\}}.$$

T_t^*

:

$$\left(A^*\} - I\right)^{-1} A^* g = f \tag{7}$$

A $\hat{A}$ [5]:

$$\left(\hat{A} f\right)_k = \}_k f_k - i \sum_{j=k+1}^{\infty} f_j \mathsf{s}_j \mathsf{s}_k ,$$

$$\}_k = r_k - i\frac{s_k^2}{2}. \qquad \left(\hat{A}^* f\right)_k = \bar{\}}_k f_k + i\sum_{j=1}^{k-1} f_j s_j s_k.$$

$$, \left(\frac{\hat{A}-\hat{A}^*}{i}f\right)_k = -\sum_{k=1}^{\infty}\left\langle f,\hat{g}\right\rangle g_k, \quad \hat{g}=\begin{pmatrix} s_1 \\ s_2 \\ \vdots \\ s_n \end{pmatrix} \quad (J_{rs})=-1.$$

$$, \hat{A}^*\hat{g}=\bar{\}}_k g_k + i\sum_{j=1}^{k} s_l^2 s_k = \left(\bar{\}}_k + ix_k\right)s_k, \qquad x_k=\sum_{j=1}^{k-1} s_j^2.$$

$$(7) \qquad , \qquad \hat{A}^* g = \left(\hat{A}^*\} - I\right)f$$

$$\left(\bar{\}}_k + ix_k\right)s_k = \left(\bar{\}}_k\} - 1\right)f_k + i\}\sum_{j=1}^{k-1} f_j s_j s_k \tag{8}$$

$$(8) \qquad s_k, \qquad\qquad \sim_k = \bar{\}}_k + ix_k:$$

$$\sim_k = \frac{\bar{\}}_k\}_k - 1}{s_k}f_k + i\}\sum_{j=1}^{k-1} f_j s_j.$$

$$\sim_k = y_k + i\}\sum_{j=1}^{k-1}\frac{y_j s_j^2}{\bar{\}}_j\}-1}, \qquad y_j=\frac{\bar{\}}_j\}-1}{s_j}f_j,$$

$$\sim_{k+1} = y_{k+1} + i\}\sum_{j=1}^{k}\frac{y_j s_j^2}{\bar{\}}_j\}-1}.$$

$$\sim_{k+1}-\sim_k = (y_{k+1}-y_k) + i\frac{\}y_k s_k^2}{\bar{\}}_k\}-1}.$$

$$\sim_{k+1}-\sim_k = y_{k+1} + y_k\left(\frac{i\}s_k^2}{\bar{\}}_k\}-1}-1\right)= y_{k+1}-y_k\frac{\}\}_k-1}{\bar{\}}_k\}-1}, \quad . \quad . \; \}_k=r_k-i\frac{s_k^2}{2}.$$

$$\sim_{k+1}-\sim_k = u_k, \qquad\qquad\qquad\qquad :$$

$$y_{k+1}=y_k\frac{\}\}_k-1}{\bar{\}}_k\}-1}+u_k, \; y_1=\bar{\}}_1 \tag{9}$$

$$(9) \qquad\qquad\qquad :$$

$$\begin{cases} y_{k+1} = A_k y_k + B_k \\ y_1 = \overline{\jmath}_1 \end{cases}, \qquad A_k = \frac{\}\}_k - 1}{\overline{\jmath}_k\} - 1}, \quad B_k = \mathsf{u}_k.$$

(9) :

$$y_k = A_1 A_2 \ldots A_{k-1} y_1 + \mathsf{u}_{k-1} + A_{k-1}\mathsf{u}_{k-2} + A_{k-1}A_{k-2}\mathsf{u}_{k-3} + \ldots + A_{k-1}\ldots A_2 \mathsf{u}_1,$$

$$A_1 A_2 \ldots A_{k-1} = \prod_{j=1}^{k-1} \frac{\}\}_j - 1}{\}\overline{\jmath}_j - 1},$$

$$y_k = A_1 A_2 \ldots A_{k-1} y_1 + \sum_{j=1}^{k-2}\prod_{l=j+1}^{k-1} A_l \mathsf{u}_j + \mathsf{u}_{k-1} = \overline{\jmath}_1 \prod_{j=1}^{k-1}\frac{\}\}_j - 1}{\}\overline{\jmath}_j - 1} + \mathsf{u}_{k-1} + \sum_{j=1}^{k-2}\prod_{l=j+1}^{k-1}\frac{\}\}_l - 1}{\}\overline{\jmath}_l - 1}\mathsf{u}_j =$$

$$= \overline{\jmath}_1 \prod_{j=1}^{k-1}\frac{\}\}_j - 1}{\}\overline{\jmath}_j - 1} + \mathsf{u}_{k-1} + \sum_{j=1}^{k-2}\mathsf{u}_j \prod_{l=j+1}^{k-1}\frac{\}\}_l - 1}{\}\overline{\jmath}_l - 1}.$$

$$\therefore \quad f_j = \frac{y_j \mathsf{s}_j}{\overline{\jmath}_j\} - 1},$$

$$f_k(\}) = \frac{\mathsf{s}_k \overline{\jmath}_1}{\overline{\jmath}_k\} - 1}\prod_{j=1}^{k-1}\frac{\}\}_j - 1}{\}\overline{\jmath}_j - 1} + \frac{\mathsf{s}_k}{\overline{\jmath}_k\} - 1}\mathsf{u}_{k-1} + \frac{\mathsf{s}_k}{\overline{\jmath}_k\} - 1}\sum_{j=1}^{k-2}\mathsf{u}_j \prod_{l=j+1}^{k-1}\frac{\}\}_l - 1}{\}\overline{\jmath}_l - 1},$$

$$\Lambda_k(t) = -\frac{1}{2fi}\oint_\chi e^{-i\}t}\left(\frac{\mathsf{s}_k \overline{\jmath}_1}{\overline{\jmath}_k\} - 1}\prod_{j=1}^{k-1}\frac{\}\}_j - 1}{\}\overline{\jmath}_j - 1} + \frac{\mathsf{s}_k}{\overline{\jmath}_k\} - 1}\mathsf{u}_{k-1} + \frac{\mathsf{s}_k}{\overline{\jmath}_k\} - 1}\sum_{j=1}^{k-2}\mathsf{u}_j \prod_{l=j+1}^{k-1}\frac{\}\}_l - 1}{\}\overline{\jmath}_l - 1}\right)d\}$$

$$, \qquad k = 1, \quad f_1(\}) = \frac{y_1 \mathsf{s}_1}{\overline{\jmath}_1\} - 1} = \frac{\overline{\jmath}_1 \mathsf{s}_1}{\overline{\jmath}_1\} - 1}.$$

$$\Lambda_1(t) = \mathsf{s}_1 e^{\frac{it}{\}_1}}.$$

$$k = 2, \quad , \qquad\qquad , \quad f_2(\}) = \frac{\mathsf{s}_2}{\overline{\jmath}_2\} - 1}\cdot\left(\frac{\overline{\jmath}_1(\}_1\} - 1)}{\overline{\jmath}_1\} - 1} + \overline{\jmath}_2 - \}_1\right).$$

$$\}_1 \neq \}_2 \qquad\qquad \Lambda_2(t) = \frac{\mathsf{s}_2}{\}_2 - \}_1}\cdot\left(e^{\frac{it}{\}_1}}\left(\}_2 + i\mathsf{s}_1^2\right) + e^{\frac{it}{\}_2}}\left(\}_1 + i\mathsf{s}_1^2\right)\right).$$

$$\}_1 = \}_2, \quad f_2(\}) = \frac{\mathsf{s}_2}{\overline{\jmath}_1\} - 1}\cdot\left(\frac{\}_1\overline{\jmath}_1\} - \overline{\jmath}_1 + i\mathsf{s}_1^2\overline{\jmath}_1\} - i\mathsf{s}_1^2}{\overline{\jmath}_1\} - 1}\right),$$

$$\Lambda_2(t) = \frac{s_2}{\}_1^2} e^{\frac{it}{\}_1}} \left(-t s_1^2 + \}_1^2 \right).$$

$$\dim \frac{\overline{A - A^*}}{i} H = 1 \qquad x_0 = \hat{g}. \qquad , \qquad \dim l_2 = 1,$$

$$V(t,s) = \frac{|x_0(1)|^2 \cdot s_1^2}{|\}_1|^2} e^{\frac{i\left(t\overline{\}}_1 - s\}_1\right)}{|\}_1|^2}} , \quad \hat{g} = \}_1, \quad \}_1 = \mathsf{r}_1 - \frac{i s_1^2}{2}.$$

$$(6) \qquad :$$

$$K(t,s) = \begin{cases} x_0(1) s_1 e^{\frac{i(t-s)}{\}_1}} + |x_0(1)|^2 i \left(e^{\frac{i\}_1(t-s)}{|\}_1|^2}} - e^{\frac{i\left(t\overline{\}}_1 - s\}_1\right)}{|\}_1|^2}} \right), & t \geq s \\[3em] \overline{x_0(1)} s_1 e^{-\frac{i(s-t)}{\overline{\}}_1}} + |x_0(1)|^2 i \left(e^{\frac{i\}_1(t-s)}{|\}_1|^2}} - e^{\frac{i\left(t\overline{\}}_1 - s\}_1\right)}{|\}_1|^2}} \right), & s \geq t. \end{cases}$$

$$\dim l_2 = 2, \qquad \}_1 \neq \}_2 \qquad x_0(1) = s_1, \, x_0(2) = s_2$$

$$V(t,s) = |x_0(1)|^2 \cdot \frac{s_1^2}{|\}_1|^2} e^{\frac{i\left(\overline{\}}_1 t - \}_1 s\right)}{|\}_1|^2}} \;+$$

$$+ x_0(1)\overline{x_0(2)} \cdot \frac{s_1 s_2}{\}_1\left(\overline{\}}_2 - \overline{\}}_1\right)} \left(\frac{\overline{\}}_2 - i s_1^2}{\overline{\}}_1} e^{\frac{i\left(\overline{\}}_1 t - \}_1 s\right)}{|\}_1|^2}} + \frac{\overline{\}}_1 - i s_1^2}{\overline{\}}_2} e^{\frac{i\left(\overline{\}}_2 t - \}_1 s\right)}{\}_1 \overline{\}}_2}} \right) +$$

$$+ x_0(2)\overline{x_0(1)} \cdot \frac{s_1 s_2}{\overline{\}}_1\left(\}_2 - \}_1\right)} \left(\left(\}_2 + i s_1^2\right) e^{\frac{i\left(\overline{\}}_1 t - \}_1 s\right)}{|\}_1|^2}} + \left(\}_1 + i s_1^2\right) e^{\frac{i\left(\overline{\}}_1 t - \}_2 s\right)}{\overline{\}}_1 \}_2}} \right) +$$

$$+ |x_0(2)|^2 \cdot \frac{s_1^2}{\left(\overline{\}}_2 - \overline{\}}_1\right)\left(\}_2 - \}_1\right)} \cdot \frac{\left(\overline{\}}_2 - i s_1^2\right)\left(\}_2 + i s_1^2\right)}{|\}_1|^2} e^{\frac{i\left(\overline{\}}_1 t - \}_1 s\right)}{|\}_1|^2}} \;+$$

$$+ |x_0(2)|^2 \cdot \frac{s_1^2}{(\overline{\jmath}_2 - \overline{\jmath}_1)(\jmath_2 - \jmath_1)} \cdot \frac{(\overline{\jmath}_1 - is_1^2)(\jmath_1 + is_1^2)}{|\jmath_2|^2} e^{\frac{i(\overline{\jmath}_2 t - \jmath_2 s)}{|\jmath_2|^2}} ;$$

$$K(t-s,0) = x_0(1)s_1 e^{\frac{i(t-s)}{\jmath_1}} + x_0(2)\frac{s_2}{\jmath_2 - \jmath_1}\left(e^{\frac{i(t-s)}{\jmath_1}}(\jmath_2 + is_1^2) + e^{\frac{i(t-s)}{\jmath_2}}(\jmath_1 + is_1^2) \right)$$

$t \geq s$;

$$K(0,s-t) = \overline{x_0(1)}s_1 e^{-\frac{i(s-t)}{\overline{\jmath}_1}} + \overline{x_0(2)}\frac{s_2}{\overline{\jmath}_2 - \overline{\jmath}_1}\left(e^{-\frac{i(s-t)}{\overline{\jmath}_1}}(\overline{\jmath}_2 - is_1^2) + e^{-\frac{i(s-t)}{\overline{\jmath}_2}}(\overline{\jmath}_1 - is_1^2) \right)$$

$s \geq t$.

$$K(t-s,0) = \langle T_t x_0, x_0 \rangle_{H_<} = \langle x_0, T_t^* x_0 \rangle_{H_<} ,$$

$$T_t^* x_0 = -\frac{1}{2fi}\oint_{\chi} e^{-i\jmath t}\left(A^*\jmath - I\right)^{-1} A^* x_0 d\jmath .$$

$$x_0 = \hat{g} , \qquad \langle T_t x_0, x_0 \rangle_{H_<} = \left\langle T_t \hat{g}, \hat{g} \right\rangle_{H_<} = \sum_{k=1}^{\infty} \hat{g}(k)\Lambda_k'(t).$$

$x_0 \neq \hat{g}$,

x_0 :

$$\left(\overset{\wedge}{A^*}\jmath - I \right)^{-1} \overset{\wedge}{A^*} x_0 = f .$$

$$\overset{\wedge}{A^*} x_0 = \left(\overset{\wedge}{A^*}\jmath - I \right) f .$$

.

$$\overset{\wedge}{A^*} x_0 = \overline{\jmath}_k x_0(k) + i\sum_{j=1}^{k} x_0(j)s_j s_k .$$

$$\left(\hat{A}{}^{*}x_0\right)_k = \dagger_k . \qquad\qquad ,$$

$$\dagger_k = \left(\bar{\}}_k - 1\right)f_k + i\}\sum_{j=1}^{k-1} f_j \mathsf{s}_j \mathsf{s}_k . \qquad (10)$$

(10) $y_k:$

$$y_{k+1} = \frac{\}_k - 1}{\bar{\}}_k - 1}\, y_k + \mathsf{u}_k,\ \ y_1 = \frac{\dagger_1}{\mathsf{s}_1}, \qquad (11)$$

$$y_k = \frac{\left(\bar{\}}_k - 1\right)}{\mathsf{s}_k} f_k ,\ \ \sim_k = \frac{\dagger_k}{\mathsf{s}_k},\ \ \}_k = \mathsf{r}_k - i\frac{\mathsf{s}_k^2}{2},\ \ \sim_{k+1} - \sim_k = \mathsf{u}_k ,$$

$$\sim_{k+1} = y_{k+1} + i\}\sum_{j=1}^{k} \frac{y_j \mathsf{s}_j^2}{\bar{\}}_j - 1} .$$

$$\sim_{k+1} - \sim_k = y_{k+1} - y_k + i\}\frac{y_k \mathsf{s}_k^2}{\bar{\}}_k - 1} ,$$

$$\sim_{k+1} - \sim_k = y_{k+1} - \left(-\frac{i\}\mathsf{s}_k^2}{\bar{\}}_k - 1} + 1\right)y_k = y_{k+1} - \frac{\bar{\}}_k - 1 - i\}\mathsf{s}_k^2}{\bar{\}}_k - 1}\, y_k = y_{k+1} - \frac{\}_k - 1}{\bar{\}}_k - 1}\, y_k .$$

$$\sim_{k+1} - \sim_k = \mathsf{u}_k , \qquad\qquad\qquad :$$

$$y_{k+1} = \frac{\}_k - 1}{\bar{\}}_k - 1}\, y_k + \mathsf{u}_k,\ \ y_1 = \frac{\dagger_1}{\mathsf{s}_1}. \qquad (11)$$

(11)   :

$$\begin{cases} y_{k+1} = A_k y_k + \mathsf{u}_k \\ y_1 = \dfrac{\dagger_1}{\mathsf{s}_1} \end{cases}, \qquad A_k = \frac{\}_k - 1}{\bar{\}}_k - 1},\ B_k = \mathsf{u}_k .$$

(11)   :

$$y_k = A_1 A_2 \ldots A_{k-1}\frac{\dagger_1}{\mathsf{s}_1} + \mathsf{u}_{k-1} + A_{k-1}\mathsf{u}_{k-2} + A_{k-1}A_{k-2}\mathsf{u}_{k-3} + \ldots + A_{k-1}\ldots A_2 \mathsf{u}_1 ,$$

$$A_1 A_2 \ldots A_{k-1} = \prod_{j=1}^{k-1}\frac{\}_j - 1}{\bar{\}}_j - 1} ,$$

$$y_k = A_1 A_2 \ldots A_{k-1} \frac{\dagger_1}{s_1} + \sum_{j=1}^{k-2} \prod_{l=j+1}^{k-1} A_l u_j + u_{k-1} = \frac{\dagger_1}{s_1} \cdot \prod_{j=1}^{k-1} \frac{\}\}_j - 1}{\}\overline{\}}_j - 1} + u_{k-1} + \sum_{j=1}^{k-2} \prod_{l=j+1}^{k-1} \frac{\}\}_l - 1}{\}\overline{\}}_l - 1} u_j =$$

$$= \frac{\dagger_1}{s_1} \cdot \prod_{j=1}^{k-1} \frac{\}\}_j - 1}{\}\overline{\}}_j - 1} + u_{k-1} + \sum_{j=1}^{k-2} u_j \prod_{l=j+1}^{k-1} \frac{\}\}_l - 1}{\}\overline{\}}_l - 1} .$$

$$\cdot \quad \cdot \quad f_j = \frac{y_j s_j}{\overline{\}}_j \} - 1} ,$$

$$f_k(\}) = \frac{s_k}{\overline{\}}_k \} - 1} \prod_{j=1}^{k-1} \frac{\}\}_j - 1}{\}\overline{\}}_j - 1} \cdot \frac{\dagger_1}{s_1} + \frac{s_k}{\overline{\}}_k \} - 1} u_{k-1} + \frac{s_k}{\overline{\}}_k \} - 1} \sum_{j=1}^{k-2} u_j \prod_{l=j+1}^{k-1} \frac{\}\}_l - 1}{\}\overline{\}}_l - 1} ,$$

$$M_k(t) =$$

$$= -\frac{1}{2fi} \oint_x e^{-i\}t} \left(\frac{s_k}{\overline{\}}_k \} - 1} \cdot \frac{\dagger_1}{s_1} \prod_{j=1}^{k-1} \frac{\}\}_j - 1}{\}\overline{\}}_j - 1} + \frac{s_k}{\overline{\}}_k \} - 1} u_{k-1} + \frac{s_k}{\overline{\}}_k \} - 1} \sum_{j=1}^{k-2} u_j \prod_{l=j+1}^{k-1} \frac{\}\}_l - 1}{\}\overline{\}}_l - 1} \right) d\}$$

$$, \quad k = 1 , \quad y_1 = \frac{\dagger_1}{s_1} , \quad f_1(\}) = \frac{y_1 s_1}{\overline{\}}_1 \} - 1} = \frac{\dagger_1}{\overline{\}}_1 \} - 1} .$$

$$M_1(t) = \frac{\dagger_1}{\}_1} e^{\frac{it}{\}_1}} .$$

$$k = 2 , \quad f_2(\}) = \frac{1}{\overline{\}}_2 \} - 1} \cdot \left(\frac{\dagger_1 s_2 \}_1 \} + \dagger_2 s_1 \overline{\}}_1 \} - \dagger_1 s_2 \overline{\}}_1 \} - \dagger_2 s_1}{s_1 (\overline{\}}_1 \} - 1)} \right) .$$

$$\}_1 \neq \}_2 \qquad :$$

$$M_2(t) = \frac{1}{s_1 (\}_2 - \}_1)} \left[e^{\frac{it}{\}_1}} \cdot \frac{i \dagger_1 s_1^2 s_2}{\}_1} - e^{\frac{it}{\}_2}} \cdot \frac{i \dagger_1 s_1^2 s_2 + \dagger_2 s_1 (\}_1 - \}_2)}{\}_2} \right] .$$

$$\}_1 = \}_2 , \quad f_2(\}) = \left(\frac{\dagger_1 s_2 \}_1 \} + \dagger_2 s_1 \overline{\}}_1 \} - \dagger_1 s_2 \overline{\}}_1 \} - \dagger_2 s_1}{s_1 (\overline{\}}_1 \} - 1)^2} \right) .$$

$$M_2(t) = \frac{1}{s_1 \}_1^2} e^{\frac{it}{\}_1}} \left(-\frac{t \dagger_1 s_1^2 s_2}{\}_1} + i \dagger_1 s_1^2 s_2 + \dagger_2 s_1 \}_1 \right) .$$

$$,$$

$$k=1 \quad V(t,s)=\left|x_0(1)\right|^2\cdot\frac{\left|\dagger_1\right|^2}{\left|\}_1\right|^2}\,e^{\frac{i\left(\overline{\}}_1 t-\}_1 s\right)}{\left|\}_1\right|^2}}. \qquad (6):$$

$$K(t,s)=x_0(1)\frac{\dagger_1}{\}_1}e^{\frac{i(t-s)}{\}_1}}+$$

$$+x_0(2)\frac{1}{s_1(\}_2-\}_1)}\left(e^{\frac{i(t-s)}{\}_1}}\cdot\frac{i\dagger_1 s_1^2 s_2}{\}_1}-e^{\frac{i(t-s)}{\}_2}}\cdot\frac{i\dagger_1 s_1^2 s_2+\dagger_2 s_1(\}_1-\}_2)}{\}_2}\right)+$$

$$+\frac{\left|x_0(1)\right|^2\cdot\left|\dagger_1\right|^2}{\left|\}_1\right|^2\cdot s_1^2}e^{\frac{i\left(t\overline{\}}_1-s\}_1\right)}{\left|\}_1\right|^2}}\left(1-e^{\frac{s_1^2 s}{\left|\}_1\right|^2}}\right),\ t\geq s$$

$$K(t,s)=\overline{x_0(1)}\frac{\dagger_1}{\overline{\}}_1}e^{-\frac{i(s-t)}{\overline{\}}_1}}-$$

$$-\overline{x_0(2)}\frac{1}{s_1(\overline{\}}_2-\overline{\}}_1)}\left(e^{-\frac{i(s-t)}{\overline{\}}_1}}\cdot\frac{i\dagger_1 s_1^2 s_2}{\overline{\}}_1}-e^{-\frac{i(s-t)}{\overline{\}}_2}}\cdot\frac{i\dagger_1 s_1^2 s_2+\dagger_2 s_1(\overline{\}}_1-\overline{\}}_2)}{\overline{\}}_2}\right)+$$

$$+\frac{\left|x_0(1)\right|^2\cdot\left|\dagger_1\right|^2}{\left|\}_1\right|^2\cdot s_1^2}e^{\frac{i\left(t\overline{\}}_1-s\}_1\right)}{\left|\}_1\right|^2}}\left(1-e^{\frac{s_1^2 t}{\left|\}_1\right|^2}}\right),\ s\geq t\ ;$$

$$k=2\ (\}_1\neq\}_2)$$

$$K(t-s,0)=x_0(1)\frac{\dagger_1}{\}_1}e^{\frac{i(t-s)}{\}_1}}+$$

$$+x_0(2)\frac{1}{s_1(\}_2-\}_1)}\left(e^{\frac{i(t-s)}{\}_1}}\cdot\frac{i\dagger_1 s_1^2 s_2}{\}_1}-e^{\frac{i(t-s)}{\}_2}}\cdot\frac{i\dagger_1 s_1^2 s_2+\dagger_2 s_1(\}_1-\}_2)}{\}_2}\right),\ t\geq s\ ;$$

$$K(0,s-t)=\overline{x_0(1)}\frac{\dagger_1}{\overline{\}}_1}e^{-\frac{i(s-t)}{\overline{\}}_1}}-$$

$$-\overline{x_0(2)}\frac{1}{s_1(\overline{\}}_2-\overline{\}}_1)}\left(e^{-\frac{i(s-t)}{\overline{\}}_1}}\cdot\frac{i\dagger_1 s_1^2 s_2}{\overline{\}}_1}-e^{-\frac{i(s-t)}{\overline{\}}_2}}\cdot\frac{i\dagger_1 s_1^2 s_2+\dagger_2 s_1(\overline{\}}_1-\overline{\}}_2)}{\overline{\}}_2}\right),\ s\geq t\ ;$$

$$V(t,s)=\left|x_0(1)\right|^2\cdot\frac{\left|\dagger_1\right|^2}{\left|\}_1\right|^4}e^{\frac{i\left(\bar{\}}_1t-\}_1s\right)}{\left|\}_1\right|^2}}+$$

$$+x_0(1)\overline{x_0(2)}\cdot\frac{\dagger_1i}{\left|\}_1\right|^4\bar{\}}_1}\left(\frac{i\dagger_1s_1^2s_2}{\bar{\}}_1}s-2\dagger_1s_1^2s_2-i\dagger_2s_1\bar{\}}_1\right)-$$

$$-\overline{x_0(1)}x_0(2)\cdot\frac{\dagger_1i}{s_1\left|\}_1\right|^4\}_1}\left(-\frac{i\dagger_1s_1^2s_2}{\}_1}t-2\dagger_1s_1^2s_2+i\dagger_2s_1\}_1\right)e^{\frac{i\left(\bar{\}}_1t-\}_1s\right)}{\left|\}_1\right|^2}}+$$

$$+\left|x_0(2)\right|^2\cdot\frac{1}{s_1^2\left|\}_1\right|^6}\left(-\frac{i\dagger_1s_1^2s_2}{\}_1}t-2\dagger_1s_1^2s_2+i\dagger_2s_1\}_1\right)\times$$

$$\times\left(\frac{i\dagger_1s_1^2s_2}{\bar{\}}_1}s-2\dagger_1s_1^2s_2-i\dagger_2s_1\bar{\}}_1\right)e^{\frac{i\left(\bar{\}}_1t-\}_1s\right)}{\left|\}_1\right|^2}}.$$

$$H_\triangleleft=L^2_{[0;l]}, \qquad\qquad A \quad \dim\overline{2\,\mathrm{Im}\,AH}=1$$

$$\}=0 \qquad\qquad\qquad . \qquad\qquad A$$

$$\stackrel{\wedge}{A},\ .\ .\ \stackrel{\wedge}{A}f(x)=-i\int\limits_x^l f(y)dy\ [5].$$

$$(1):$$

$$\begin{cases}\dfrac{\partial}{\partial t}\displaystyle\int\limits_x^l \triangleleft(t,u)du=-\triangleleft(t,u)\\[2mm]\triangleleft|_{t=0}=f_0(x).\end{cases}$$

$$\qquad\qquad\qquad\qquad\qquad .$$

$$\int\limits_x^l \triangleleft(t,u)du=\mathrm{y}(t,x). \qquad \mathrm{y}(t,x) \qquad\qquad\qquad :$$

$$\begin{cases}\dfrac{\partial\mathrm{y}}{\partial t}-\dfrac{\partial\mathrm{y}}{\partial x}=0\\[2mm]\mathrm{y}|_{t=0}=\displaystyle\int\limits_x^l f_0(x)dx=f_1(x).\end{cases}$$

$$[6]:$$

$$\mathrm{y}=f_1(x+t).$$

$$.\ .\ \triangleleft(x,t)=-\frac{\partial\mathrm{y}}{\partial x}, \qquad \triangleleft(x,t)=\begin{cases}f_0(x+t), & x\in[t;+\infty)\cap[0;l],\\ 0, & x\notin[t;+\infty)\cap[0;l].\end{cases}$$

$$K(t,s)=\langle \varsigma_t, \varsigma_s \rangle = \begin{cases} \int\limits_{\max(t,s)}^{l} f_0(x+t)\overline{f_0(x+s)}dx, & t,s \in [0;l], \\ 0, & t,s \notin [0;l]. \end{cases}$$

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