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## **MANAGEMENT OF REGIONAL ECONOMIC STABILITY DEVELOPMENT WITH PROCESS MODELLING OF MONITORING**

**Introduction:** stability functioning regions is accompanied by the need to identify and responding to the influence of different instability factors that are caused disturbances economic or social nature. **Objective:** to develop a model of evaluating the effectiveness of management stability of the regional economy. **Methods:** systems analysis, fuzzy logic, neural networks. **Results:** The model of evaluating the effectiveness of management stability of the regional economy that can quickly diagnose the real state of socio-economic development and timely use mechanisms that could prevent undesirable scenarios such development is constructed. **Conclusions:** solving of the complex problem of social stability and economic development lies in the organization of the monitoring system based on the construction and implementation of economic and mathematical models estimating of the situation and identify options sustainability of the region as an integrated probabilistic dynamic system.

**Keywords:** management, stability, development, regional economic, monitoring.







[6].

$$CP = f(x_1, x_2, x_3),$$

$$x_i = f_i(x_i^1, x_i^2, \dots, x_i^{q_i}), \quad (x_i^1, x_i^2, \dots, x_i^{q_i}), \quad i = 1, 2, 3$$

$$x_i \quad CP$$

$$T_i = \{t_i^1, t_i^2, \dots, t_i^{k_i}\} - x_i;$$

$$S = \{s_1, s_2, \dots, s_m\} -$$

$$x_i^\sigma, \sigma = 1, \dots, q_i, i = 1, 2, 3$$

$$T_i^\sigma = \{t_i^{\sigma 1}, t_i^{\sigma 2}, \dots, t_i^{\sigma k_i}\}.$$

$$s_j \quad k_j \quad CP.$$

$$\omega_{jl}, j = 1, \dots, m, l = 1, \dots, k_j \quad s_j, j = 1, \dots, m. \quad t_i^{js} \quad x_i, \quad k_j$$

$$s_j. \quad t_i^{js}, \quad i - \quad jl - \quad T_i.$$

$$x_1 = t_1^{11} \quad x_2 = t_2^{11} \quad x_3 = t_3^{11} \quad \omega_{11},$$

$$x_1 = t_1^{12} \quad x_2 = t_2^{12} \quad x_3 = t_3^{12} \quad \omega_{12}$$

$$x_1 = t_1^{1k_1} \quad x_2 = t_2^{1k_1} \quad x_3 = t_3^{1k_1} \quad \omega_{1k_1}$$

$$CP = s_1,$$

$$x_1 = t_1^{21} \quad x_2 = t_2^{21} \quad x_3 = t_3^{21} \quad \omega_{21},$$

$$\begin{array}{cccc}
x_1 = t_1^{22} & x_2 = t_2^{22} & x_3 = t_3^{22} & \omega_{22} \\
\hline
x_1 = t_1^{2k_2} & x_2 = t_2^{2k_2} & x_3 = t_3^{2k_2} & \omega_{2k_2}, \\
CP = s_2, & & & \\
\hline
x_1 = t_1^{m1} & x_2 = t_2^{m1} & x_3 = t_3^{m1} & \omega_{m1}, \\
x_1 = t_1^{m2} & x_2 = t_2^{m2} & x_3 = t_3^{m2} & \omega_{m2} \\
\hline
x_1 = t_1^{mk_m} & x_2 = t_2^{mk_m} & x_3 = t_3^{mk_m} & \omega_{mk_m} \\
CP = s_m. & & & 
\end{array}$$

$$\begin{array}{ccc}
t_i^{js} \quad l = 1, \dots, k_j & & \\
x_i. & & \\
\mu_{s_j}(x_1, x_2, x_3) - & (x_1, x_2, x_3) & : \\
s_j, j = 1, \dots, m & CP; & \\
\mu_{jl}(x_i) = \frac{1}{1 + \left(\frac{x_i - a_i^{jl}}{b_i^{jl}}\right)^{c_i^{jl}}} - & x_i & \\
t_i^{jl}; a_i^{jl}, b_i^{jl}, c_i^{jl} - & . & \\
l = 1, \dots, k_j, \sigma = 1, \dots, q_i & : & t_i^{\sigma j},
\end{array}$$

$$\begin{array}{c}
\mu_{\sigma j l}(x_i^\sigma) = \frac{1}{1 + \left(\frac{x_i^\sigma - a_i^{\sigma j l}}{b_i^{\sigma j l}}\right)^{c_i^{\sigma j l}}}. \\
: \\
\mu_{s_1}(x_1, x_2, x_3) = \omega_{11}(\mu_{11}(x_1) \wedge \mu_{11}(x_2) \wedge \mu_{11}(x_3)) \\
\vee \omega_{12}(\mu_{12}(x_1) \wedge \mu_{12}(x_2) \wedge \mu_{12}(x_3)) \\
\vdots \\
\vee \omega_{1k_1}(\mu_{1k_1}(x_1) \wedge \mu_{1k_1}(x_2) \wedge \mu_{1k_1}(x_3)), \\
\mu_{s_2}(x_1, x_2, x_3) = \omega_{21}(\mu_{21}(x_1) \wedge \mu_{21}(x_2) \wedge \mu_{21}(x_3)) \\
\vee \omega_{22}(\mu_{22}(x_1) \wedge \mu_{22}(x_2) \wedge \mu_{22}(x_3)) \\
\vdots \\
\vee \omega_{2k_2}(\mu_{2k_2}(x_1) \wedge \mu_{2k_2}(x_2) \wedge \mu_{2k_2}(x_3)), \\
\vdots \\
\mu_{s_m}(x_1, x_2, x_3) = \omega_{m1}(\mu_{m1}(x_1) \wedge \mu_{m1}(x_2) \wedge \mu_{m1}(x_3)) \\
\vee \omega_{m2}(\mu_{m2}(x_1) \wedge \mu_{m2}(x_2) \wedge \mu_{m2}(x_3)) \\
\vdots \\
\vee \omega_{mk_m}(\mu_{mk_m}(x_1) \wedge \mu_{mk_m}(x_2) \wedge \mu_{mk_m}(x_3)),
\end{array}$$

$$\mu_{jl}(x_i) = \mu_{jl}(x_i^1, x_i^2, \dots, x_i^{q_i}) = \omega_{ij1}(\mu_{1j1}(x_i^1) \wedge \mu_{2j1}(x_i^2) \wedge \dots \wedge \mu_{q_i j1}(x_i^{q_i})) \vee \omega_{ij2}(\mu_{1j2}(x_i^1) \wedge \mu_{2j2}(x_i^2) \wedge \dots \wedge \mu_{q_i j2}(x_i^{q_i})) \vee \dots \vee \omega_{ijk_1}(\mu_{1jk_1}(x_i^1) \wedge \mu_{2jk_1}(x_i^2) \wedge \dots \wedge \mu_{q_i jk_1}(x_i^{q_i}))$$

$\mu_{s_j}(x_1, x_2, x_3)$

min      max .

CP -

[0;1] , [0;1/4] -

", [1/4;1/2] - " , [1/2;3/4] - "

", [3/4;1] - "

CP :

$$CP = \frac{\sum_{j=1}^4 h'_j \mu_{s_j}(CP)}{\sum_{j=1}^4 \mu_{s_j}(CP)},$$

$$h'_j \in [h_{j-1}; h_j], \mu_{s_j}(CP) = \max_l \{ \omega_{jl} \min_i \{ \mu_{jl}(x_i) \} \} - t_j, j = 1, \dots, 4, l = 1, \dots, k_j.$$

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